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Programmable dynamic tracing on Linux with DTrace using BPF

dr. Kris Van Hees

Consulting Engineer, Languages and Tools Linux Engineering September 18, 2023

Overview

- **1**. Short overview of DTrace on Linux
- 2. Programmable dynamic tracing:
 - D scripts compiled into BPF programs
- 3. The 'joy' of product status...
- 4. .. and other challenges
- 5. Features we need but do not have in upstream kernels (yet)
- 6. More information... Get involved...

Short overview of DTrace on Linux

- DTrace for Linux started in 2010
- Between 2018 and 2020, DTrace transitioned from an invasive kernel/userspace implementation to a pure userspace implementation (based on kernel tracing features incl. eBPF).
- DTrace provides:
 - Combined kernel space and userspace tracing
 - C-style scripting language
 - Higher level data structures (strings, arrays, associative arrays, aggregations)
 - Scripted actions associated with probes
 - Speculative tracing
 - ...

Programmable dynamic tracing

- DTrace provides **programmable** tracing:
 - Code is written in clauses
 - Clauses are associated with probes and act like functions, executed when the probe fires
 - Predicates provide conditional clauses
 - Any number of clauses can be associated with a probe
 - Any number of probes can be associated with a clause
- DTrace provides **dynamic** tracing:
 - Scripts written in D
 - Can adapt to trace data

```
fbt::wake_up_new_task:entry
{
    self = (struct task_struct *)arg0;
    euids[self > p > tgid] = self > p > cred > euid.val;
    comms[self +> tgid] = (string)self +p + name;
}
sched_process_exit
\{ euids[pid] = 0; \}
proc:::exit
{ comms[pid] = 0; }
execve:entry
{
    this→in_execve = 1;
```

this \rightarrow uid = 0;

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}

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```
this > in_execve = 0;
}
path_openat:return
/this > in_execve && arg1 > 0 && arg1 < 4096/
{</pre>
```

execve:return

{

```
this→uid = ((struct file
*)arg1)→f_inode→i_uid.val;
}
```

```
path_openat:return
/this>execve && arg1 && comms[ppid] != 0 &&
  this>uid != 0 && this>uid != euids[ppid]/
{
    printf("...");
}
09/14/2023
```

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}
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proc:::exit
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execve:entry
    Syscall provider
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    this > uid = 0;
}
    Copyright © 2023, Oracle and/or its affiliates
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execve:return Syscall provider
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      09/14/2023
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sched_process_exit
{ euids[pid] = 0; }
proc:::exit proc-provider
{ comms[pid] = 0; }
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- Each clause is compiled into a BPF function
- DTrace probes are mapped to kernel-level probes:
 - FBT probes are mapped to kprobes
 - Syscall probes are mapped to syscall entry and return tracepoints
 - Profile probes are mapped to perf timer events
 - USDT and pid probes are mapped to uprobes
 - SDT probes (proc, sched, lockstat, ...) are mapped to any other probe
 - Sometimes a single probe, sometimes multiple probes
 - Sometimes multiple probes working together (e.g. one does setup, the other reports the firing)
- Common subroutines are implemented using pre-compiled BPF code
 - Leveraging BPF support in GCC and binutils

- A BPF program is generated for each kernel-level probe:
 - BPF program types vary across different kernel-level probes
 - BPF programs are specific to a certain program type
 - DTrace considers all probes to be essentially the same
 - Differences are reflected in naming (irrelevant) and probe arguments
 - A single clause associated with two probes of different BPF program type requires two BPF programs.
 - DTrace probes implemented on top of other DTrace probes need to appear to the consumer as distinct probes.



- The BPF program for a specific BPF probe is generated as a trampoline:
 - Exit immediately if the consumer has not started yet
 - Create a DTrace context:
 - Populate probe arguments based on the BPF context (program type specific)
 - Set up the DTrace context based on the DTrace probe information
 - Set up the output buffer and other internal pointers and data structures
 - Generate calls to all clause BPF functions for this kernel-level probe, checking before each call whether tracing is still active (global on/off switch)
 - For each (if any) (dependent) DTrace probe implemented based on this (underlying) probe:
 - Save the probe arguments
 - Morph the DTrace context into the dependent DTrace probe and call its clauses
 - Restore the probe arguments



(global on/off switch)

- The final (loadable) BPF program is then constructed using a custom linker:
 - Recursively resolve all function call references by appending the generated code for the function (clause BPF function or pre-compiled BPF function) to the program and patching the call target offset
 - Resolve all symbolic references to constants that are compilation-specific

It all sounds so easy...



It all sounds so easy...

too easy...

The 'joy' of product status...

- Since 2020, DTrace based on BPF is supported as a product on various kernel releases:
 - 5.4.x-based kernels
 - 5.15.x-based kernels
- Most development is done on newer kernels:
 - 6.1.x
 - 6.5.x
 - bpf-next

... and that has consequences!



The joy of 'product' status... (cont.) ... and other challenges

- Kernel helpers differ between kernel versions (usually more, never less)
- BPF verifier behaviour differs between kernel helpers
- Kernel implementation of target areas for tracing change (less common)
- And there is an expectation of retaining documented behaviour

Some BPF helpers are only available in newer kernels

- bpf_probe_read() and bpf_probe_read_str() can be used for kernel and userspace addresses on most architectures (but not all)
 - bpf_probe_read_kernel(), bpf_probe_read_user(), bpf_probe_read_kernel_str(), bpf_probe_read_user_str() were introduced later to resolve this
 - Some kernels versions had a confusing mix of what worked and what didn't
- bpf_get_current_task_btf() and bpf_task_pt_regs() were introduced in later kernels
 - But we still need to get to task CPU registers on older kernels also
 - We wrote some (semi-convoluted) BPF code to mimic the kernel code to determine the location of the saved userspace registers for the current task, using bpf_probe_kernel_read()s to chase pointer chains to get to our target.



- BPF verifier is meant to guarantee safety of BPF programs being loaded into the kernel
- BPF verifier allows programs to pass that it deems safe
 - But it may reject programs that are actually perfectly safe
 - It is impossible to get it right all the time
- Compiler-generated code may be safe because of how the code is generated, but the BPF verifier may not be able to ascertain that
- DTrace provides programmable dynamic tracing, so it **needs** to be able to generate programs
- We strike a balance between generating efficient code and code that is constructed to ensure it can pass the BPF verifier.



- Remember: BPF verifier implementations differ between kernel versions
- We need to be able to pass the BPF verifier on all supported kernel versions
 - Sadly, this is often a process of trial and error:
 - Analyze a rejection
 - Find a solution
 - Ensure the solution is valid on all supported kernel versions

- The BPF verifier uses static evaluation of instruction sequences to 'prove' safety
- There is a limit on how many instructions the BPF verifier will evaluate: **1 million**
 - That is a pretty low limit, because...

- The BPF verifier uses static evaluation of instruction sequences to 'prove' safety
- There is a limit on how many instructions the BPF verifier will evaluate: **1 million**
 - That is a pretty low limit, because...
 - The BPF verifier has limited state saving capabilities
 - Loops often need to evaluated for every possible input value
 - Code after a function call return may need to be evaluated for every possible return value
 - Adding in (pointless) branches can give the BPF verifier hints about value range boundaries
 - But we need to be careful no dead code allowed!
 - This is also a challenge in view of program linking... resolving symbolic constants could render a code block dead code.

- The BPF verifier's static evaluation of instruction sequences is complex
 - Predicting how the BPF verifier will evaluate your code is extremely difficult
 - And can change depending on the kernel version
 - Understanding a failure is not always enough to figure out a solution

Tracing infrastructure performance with MANY probes

- Creating a large amount of kprobes (or uprobes) is pretty slow
- Removing a large amount of kprobes (or uprobes) is very slow
 - 51351 probes took 58.37s!
- Problem seems to be located in the management of data structures at the kernel level
 - Possible solution for removals: lazy removal
 - Mark probe for removal but don't remove it from the list
 - At regular intervals, do a batch removal of "stale" probes

Features we need but do not have in upstream kernels (yet)

- DTrace probe naming is expected to be 'stable': provider:module:function:name
 - Probes in code that can be compiled as a kernel module are expected to be grouped under the module name
 - Whether the module is compiled as a loadable module or compiled into the kernel should not affect the probe naming
 - Patch submitted to upstream kernel: kallmodsyms
- DTrace makes extensive use of datatype information
 - Depending on debuginfo is unacceptable (too large)
 - CTF (Compact C Type Format) was developed for this in the early days of DTrace
 - Support is now in GCC and binutils
 - Patch to be submitted to upstream kernel: CTF

Features we need but do not have in upstream kernels yet (cont.)

- DTrace needs to be able to listen for various events using a poll interface
 - Notification of available data in perf output buffers
 - Notification of state changes of processes (pid)
 - Existing mechanisms are not adequate
 - Patch to be submitted to upstream kernel: waitfd()



More information... Get involved...

- Source code:
 - https://github.com/oracle/dtrace-utils (dev branch)
- Mailing list:
 - dtrace-devel@oss.oracle.com

Thank you!





Our mission is to help people see data in new ways, discover insights, unlock endless possibilities.